

# A Stochastic Convergence Analysis for Tikhonov-Regularization with Sparsity Constraints

D. Gerth, R. Ramlau

IFIP TC7, September 2013, Klagenfurt



- Introduction
- A Convergence Theorem
- Convergence Rates
- Numerical Examples



# Overview

- Introduction
- A Convergence Theorem
- Convergence Rates
- Numerical Examples



## Starting question

Can we prove convergence (-rates) for Tikhonov-Regularization with sparsity-penalty if instead of  $\|y - y^\delta\| \leq \delta$  an explicit stochastic error model is used?

## Starting question

Can we prove convergence (-rates) for Tikhonov-Regularization with sparsity-penalty if instead of  $\|y - y^\delta\| \leq \delta$  an explicit stochastic error model is used?

- We study the solution of the linear ill-posed problem

$$\mathbf{A}\mathbf{x} = \mathbf{y}$$

with  $\mathbf{A} \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$  where  $\mathcal{X}$  and  $\mathcal{Y}$  are Hilbert spaces.

- Basic deterministic model:

$$\|\mathbf{A}\mathbf{x} - \mathbf{y}^\delta\|^2 + \hat{\alpha}\Phi_{\mathbf{w},p}(\mathbf{x}) \rightarrow \min_{\mathbf{x}} \quad (1)$$

- Penalty  $\Phi_{\mathbf{w},p}(\mathbf{x}) = \sum_{\lambda \in \Lambda} w_\lambda |\langle \mathbf{x}, \psi_\lambda \rangle|^p$  for an ONB  $\{\psi_\lambda\}$

- computation requires discretization, done via projections

$$P_m : \mathcal{Y} \rightarrow \mathbb{R}^m, \quad \mathbf{y} \mapsto y, \quad \text{e.g. point evaluation}$$

$$T_n : \mathcal{X} \rightarrow \mathbb{R}^n, \quad x = T_n \mathbf{x} = \{\langle \mathbf{x}, \psi_i \rangle\}_{i=1, \dots, n}$$

$$T_n^* : \mathbb{R}^n \rightarrow \mathcal{X}, \quad \mathbf{x}_n = \sum_{i=1}^n \langle \mathbf{x}, \psi_i \rangle \psi_i$$

where  $\{\psi_i\}_{i=1}^{\infty}$  is ONB in  $\mathcal{X}$ .

- computation requires discretization, done via projections

$$P_m : \mathcal{Y} \rightarrow \mathbb{R}^m, \quad \mathbf{y} \mapsto y, \quad \text{e.g. point evaluation}$$

$$T_n : \mathcal{X} \rightarrow \mathbb{R}^n, \quad x = T_n \mathbf{x} = \{\langle \mathbf{x}, \psi_i \rangle\}_{i=1, \dots, n}$$

$$T_n^* : \mathbb{R}^n \rightarrow \mathcal{X}, \quad \mathbf{x}_n = \sum_{i=1}^n \langle \mathbf{x}, \psi_i \rangle \psi_i$$

where  $\{\psi_i\}_{i=1}^{\infty}$  is ONB in  $\mathcal{X}$ .

- each component of  $y$  carries *stochastic noise*,  $y^\sigma = y + \varepsilon$ ,  
 $\varepsilon \sim \mathcal{N}(0, \sigma^2 I_m)$ .

- computation requires discretization, done via projections

$$P_m : \mathcal{Y} \rightarrow \mathbb{R}^m, \quad \mathbf{y} \mapsto y, \quad \text{e.g. point evaluation}$$

$$T_n : \mathcal{X} \rightarrow \mathbb{R}^n, \quad x = T_n \mathbf{x} = \{\langle \mathbf{x}, \psi_i \rangle\}_{i=1, \dots, n}$$

$$T_n^* : \mathbb{R}^n \rightarrow \mathcal{X}, \quad \mathbf{x}_n = \sum_{i=1}^n \langle \mathbf{x}, \psi_i \rangle \psi_i$$

where  $\{\psi_i\}_{i=1}^{\infty}$  is ONB in  $\mathcal{X}$ .

- each component of  $y$  carries *stochastic* noise,  $y^\sigma = y + \varepsilon$ ,  $\varepsilon \sim \mathcal{N}(0, \sigma^2 I_m)$ .
- Define  $A := P_m \mathbf{A} T_n^*$ , then we want to find  $x$  s.t.

$$Ax = y^\sigma \tag{2}$$



## We use Bayes' formula

to calculate the solution. In this framework, every quantity is treated as a random variable in a complete probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

$$\pi_{post}(x|y^\sigma) = \frac{\pi_\varepsilon(y^\sigma|x)\pi_{pr}(x)}{\pi_{y^\sigma}(y^\sigma)}.$$

- $\pi_{post}(x|y^\sigma)$  posterior density
- $\pi_\varepsilon(y^\sigma|x)$  likelihood function
- $\pi_{pr}(x)$  prior distribution
- $\pi_{y^\sigma}(y^\sigma)$  data distribution (irrelevant)

## We use Bayes' formula

to calculate the solution. In this framework, every quantity is treated as a random variable in a complete probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

$$\pi_{post}(x|y^\sigma) = \frac{\pi_\varepsilon(y^\sigma|x)\pi_{pr}(x)}{\pi_{y^\sigma}(y^\sigma)}.$$

- $\pi_{post}(x|y^\sigma)$  posterior density
- $\pi_\varepsilon(y^\sigma|x)$  likelihood function
- $\pi_{pr}(x)$  prior distribution
- $\pi_{y^\sigma}(y^\sigma)$  data distribution (irrelevant)

gaussian error model:

$$\pi_\varepsilon \propto \exp\left(-\frac{1}{2\sigma^2} \|Ax - y^\sigma\|^2\right),$$

# Besov spaces

- We are looking for sparse reconstructions w.r.t. a basis in  $\mathcal{X}$
- our choice: Besov-Space  $B_{p,q}^s(\mathbb{R}^d)$  prior (notation:  $B_p^s(\mathbb{R}^d)$  )
- Reasons:
  - "easy" characterization with coefficients of a wavelet expansion
  - sparsity-promoting properties
  - discretization invariance (Lassas, Saksman, Siltanen '09)

## Definition of the wavelet expansion

Let  $\phi \in C^{\tilde{s}}(\mathbb{R})$  be a scaling function and  $\psi \in C^{\tilde{s}}(\mathbb{R})$  a compactly supported wavelet,  $\tilde{s} > s$  and define

$$\begin{aligned}\phi_{j,k}(t) &= 2^{\frac{j}{2}} \phi(2^j t - k), \\ \psi_{j,k}(t) &= 2^{\frac{j}{2}} \psi(2^j t - k), \quad j, k \in \mathbb{Z}.\end{aligned}$$

such that the collection  $\{\psi_{j,k} : j, k \in \mathbb{Z}\}$  constitutes an orthonormal basis of  $L_2(\mathbb{R})$  and for each  $\mathbf{h} \in L_2(\mathbb{R})$  we have

$$\mathbf{h} = \sum_{k=-\infty}^{\infty} \langle \mathbf{h}, \phi_{0,k} \rangle \phi_{0,k} + \sum_{j=0}^{\infty} \sum_{k=-\infty}^{\infty} \langle \mathbf{h}, \psi_{j,k} \rangle \psi_{j,k}.$$

## Definition of the wavelet expansion

Let  $\phi \in C^{\tilde{s}}(\mathbb{R})$  be a scaling function and  $\psi \in C^{\tilde{s}}(\mathbb{R})$  a compactly supported wavelet,  $\tilde{s} > s$  and define

$$\begin{aligned}\phi_{j,k}(t) &= 2^{\frac{j}{2}} \phi(2^j t - k), \\ \psi_{j,k}(t) &= 2^{\frac{j}{2}} \psi(2^j t - k), \quad j, k \in \mathbb{Z}.\end{aligned}$$

such that the collection  $\{\psi_{j,k} : j, k \in \mathbb{Z}\}$  constitutes an orthonormal basis of  $L_2(\mathbb{R})$  and for each  $\mathbf{h} \in L_2(\mathbb{R})$  we have

$$\mathbf{h} = \sum_{k=-\infty}^{\infty} \langle \mathbf{h}, \phi_{0,k} \rangle \phi_{0,k} + \sum_{j=0}^{\infty} \sum_{k=-\infty}^{\infty} \langle \mathbf{h}, \psi_{j,k} \rangle \psi_{j,k}.$$

assumption:

only finitely many nonzero scalar products on each scale



- with this, a  $d$ -dimensional basis can be constructed
- let  $\{\psi_\lambda : \lambda \in \Lambda\}$  denote the set of all wavelets  $\psi$ , also including the scaling functions  $\phi$  where  $\Lambda$  is an appropriate index set, possibly infinite
- set  $|\lambda| = j$ , then
- $\mathbf{x} \in B_p^s(\mathbb{R}^d) \subset L^2(\mathbb{R}^d)$ ,  $s < \tilde{s}$ , if

$$\|\mathbf{x}\|_{B_p^s} := \left( \sum_{\lambda \in \Lambda} \underbrace{2^{\varsigma p |\lambda|}}_{w_\lambda} |\langle \mathbf{x}, \psi_\lambda \rangle|^p \right)^{1/p} < \infty$$

and  $\varsigma = s + d(\frac{1}{2} - \frac{1}{p}) \geq 0$ . We focus on  $1 \leq p \leq 2$ .

# Besov-space random variables

Definition (adapted from Lassas/Saksman/Siltanen, 2009)

Let  $1 \leq p < \infty$  and  $s \in \mathbb{R}$ . Let  $U$  be the random function

$$U(t) = \sum_{\lambda \in \Lambda} 2^{-s|\lambda|} X_{\lambda}^{\alpha} \psi_{\lambda}(t), \quad t \in \mathbb{R}^d,$$

where the coefficients  $(X_{\lambda}^{\alpha})_{\lambda \in \Lambda}$  are independent identically distributed real-valued random variables with probability density function

$$\pi_X(\tau) = c_p^{\alpha} \exp\left(-\frac{\alpha|\tau|^p}{2}\right), \quad c_p^{\alpha} = \left(\frac{\alpha}{2}\right)^{\frac{1}{p}} \frac{p}{2\Gamma(\frac{1}{p})}, \quad \tau \in \mathbb{R}.$$

Then we say  $U$  is distributed according to a  $B_p^s$ -prior,  $U \propto \exp\left(-\frac{\alpha}{2} \|U\|_{B_p^s}^p\right)$ .



“Problem”:  $\mathbb{P}(U \in B_p^s(\mathbb{R}^d)) = 0$



“Problem”:  $\mathbb{P}(U \in B_p^s(\mathbb{R}^d)) = 0$

Theorem (adapted from Lassas/Saksman/Siltanen, 2009)

Let  $U$  be a  $B_p^s$ -random function defined as before,  $2 < \alpha < \infty$  and take  $r \in \mathbb{R}$ . Then the following three conditions are equivalent:

- (i)  $\|U\|_{B_p^r(\mathbb{R}^d)} < \infty$  almost surely,
- (ii)  $\mathbb{E} \exp\left(\|U\|_{B_p^r(\mathbb{R}^d)}^p\right) < \infty$ ,
- (iii)  $r < s - \frac{d}{p}$ .

same result as [LSS 2009], but here  $\mathbb{R}^d$  instead of  $\mathbb{T}^d$  considered



## How to avoid this phenomenon?

- “finite model” (MI)
  - consider discretization level  $n < \infty$  fixed, finite index set  $\Lambda_n$
  - Then

$$X_n(t) := \sum_{\lambda \in \Lambda_n} 2^{-s|\lambda|} X_\lambda^\alpha \psi_\lambda(t) \Rightarrow \|X_n\|_{B_p^s}^p = \sum_{\lambda \in \Lambda_n} |X_\lambda^\alpha|^p < \infty$$

- and  $\mathbb{P}(\|X_n\|_{B_p^s} > \varrho) = \frac{\Gamma(\frac{n}{p}, \frac{\alpha \varrho^p}{2})}{\Gamma(\frac{n}{p})} \leq \frac{1}{\varrho} \sqrt[p]{\frac{2n}{\alpha p}}$
- “infinite model” (MII)

## How to avoid this phenomenon?

- “finite model” (MI)

- consider discretization level  $n < \infty$  fixed, finite index set  $\Lambda_n$
- Then

$$X_n(t) := \sum_{\lambda \in \Lambda_n} 2^{-s|\lambda|} X_\lambda^\alpha \psi_\lambda(t) \Rightarrow \|X_n\|_{B_p^s}^p = \sum_{\lambda \in \Lambda_n} |X_\lambda^\alpha|^p < \infty$$

- and  $\mathbb{P}(\|X_n\|_{B_p^s} > \varrho) = \frac{\Gamma(\frac{n}{p}, \frac{\alpha \varrho^p}{2})}{\Gamma(\frac{n}{p})} \leq \frac{1}{\varrho} \sqrt{\frac{2n}{\alpha p}}$

- “infinite model” (MII)

- forget about discretization level  $n$
- define  $X(t)$  in  $B_p^r(\mathbb{R}^d)$  with  $s < r - \frac{d}{p}$ , then
- $\mathbb{E}(\|X\|_{B_p^s(\mathbb{R}^d)}) = \left( \frac{2}{\alpha p} \left( c_\lambda^1 + c_\lambda^2 \sum_{j=0}^{\infty} 2^{-j((r-s)p-d)} \right) \right)^{\frac{1}{p}} < \infty$
- and  $\mathbb{P}(\|X\|_{B_p^s} > \varrho) \leq \frac{1}{\varrho} \mathbb{E}(\|X\|_{B_p^s(\mathbb{R}^d)})$

## Recall

$$\pi_{post}(x|y^\sigma) = \frac{\pi_{pr}(x)\pi_\varepsilon(y^\sigma|x)}{\pi_{y^\sigma}(y^\sigma)}.$$

$\pi_\varepsilon(y^\sigma|x)$  gaussian noise,  $\pi_{pr}(x)$  Besov-Space prior

$$\Rightarrow \pi_{post}(x|y^\sigma) \propto \exp\left(-\frac{1}{2\sigma^2}\|Ax - y^\sigma\|^2\right) \cdot \exp\left(-\frac{\alpha}{2}\|T_n^*x\|_{B_p^s}^p\right)$$

## Recall

$$\pi_{post}(x|y^\sigma) = \frac{\pi_{pr}(x)\pi_\varepsilon(y^\sigma|x)}{\pi_{y^\sigma}(y^\sigma)}.$$

$\pi_\varepsilon(y^\sigma|x)$  gaussian noise,  $\pi_{pr}(x)$  Besov-Space prior

$$\Rightarrow \pi_{post}(x|y^\sigma) \propto \exp\left(-\frac{1}{2\sigma^2}\|Ax - y^\sigma\|^2\right) \cdot \exp\left(-\frac{\alpha}{2}\|T_n^*x\|_{B_p^s}^p\right)$$

we are interested in the *maximum a-priori* solution

$$x_{\text{map}} = \operatorname{argmax}_{x \in \mathbb{R}^n} \pi_{post}(x|y^\sigma)$$

or equivalently

$$x_\alpha^{\text{map}} = \operatorname{argmin}_{x \in \mathbb{R}^n} \left\|Ax - y^\sigma\right\|^2 + \alpha\sigma^2\|T_n^*x\|_{B_p^s(\mathbb{R}^d)}^p \quad (3)$$

## Recall

$$\pi_{post}(x|y^\sigma) = \frac{\pi_{pr}(x)\pi_\varepsilon(y^\sigma|x)}{\pi_{y^\sigma}(y^\sigma)}.$$

$\pi_\varepsilon(y^\sigma|x)$  gaussian noise,  $\pi_{pr}(x)$  Besov-Space prior

$$\Rightarrow \pi_{post}(x|y^\sigma) \propto \exp\left(-\frac{1}{2\sigma^2}\|Ax - y^\sigma\|^2\right) \cdot \exp\left(-\frac{\alpha}{2}\|T_n^*x\|_{B_p^s}^p\right)$$

we are interested in the *maximum a-priori* solution

$$x_{\text{map}} = \operatorname{argmax}_{x \in \mathbb{R}^n} \pi_{post}(x|y^\sigma)$$

or equivalently

$$x_\alpha^{\text{map}} = \operatorname{argmin}_{x \in \mathbb{R}^n} \left\| Ax - y^\sigma \right\|^2 + \underbrace{\alpha\sigma^2}_{\hat{\alpha}} \|T_n^*x\|_{B_p^s(\mathbb{R}^d)}^p \quad (3)$$

same functional as in deterministic case, but  $\|y - y^\sigma\| \leq \delta$  does not hold

- stochastic setting requires different measure for convergence
- convergence in expectation may be too strict
- instead, we use the *Ky Fan metric*

### Definition

Let  $x_1$  and  $x_2$  be random variables in a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  with values in a metric space  $(\mathcal{X}, d_{\mathcal{X}})$ . The distance between  $x_1$  and  $x_2$  in the *Ky Fan metric* is defined as

$$\rho_K(x_1, x_2) := \inf\{\epsilon > 0 : \mathbb{P}(d_{\mathcal{X}}(x_1(\omega), x_2(\omega)) > \epsilon) < \epsilon\}.$$



- stochastic setting requires different measure for convergence
- convergence in expectation may be too strict
- instead, we use the *Ky Fan metric*

### Definition

Let  $x_1$  and  $x_2$  be random variables in a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  with values in a metric space  $(\mathcal{X}, d_{\mathcal{X}})$ . The distance between  $x_1$  and  $x_2$  in the *Ky Fan metric* is defined as

$$\rho_K(x_1, x_2) := \inf\{\epsilon > 0 : \mathbb{P}(d_{\mathcal{X}}(x_1(\omega), x_2(\omega)) > \epsilon) < \epsilon\}.$$

- allows combination of deterministic and stochastic quantities



- stochastic setting requires different measure for convergence
- convergence in expectation may be too strict
- instead, we use the *Ky Fan metric*

### Definition

Let  $x_1$  and  $x_2$  be random variables in a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  with values in a metric space  $(\mathcal{X}, d_{\mathcal{X}})$ . The distance between  $x_1$  and  $x_2$  in the *Ky Fan metric* is defined as

$$\rho_K(x_1, x_2) := \inf\{\epsilon > 0 : \mathbb{P}(d_{\mathcal{X}}(x_1(\omega), x_2(\omega)) > \epsilon) < \epsilon\}.$$

- allows combination of deterministic and stochastic quantities
- metric for convergence in probability

## Ky Fan error estimate

### Theorem (Neubauer, Pikkarainen, 2008)

Let  $y^\sigma$  be a random variable with values in  $\mathbb{R}^m$ . Assume that the distribution of  $y^\sigma$  is  $\mathcal{N}(y, \sigma^2 I)$  with  $\sigma > 0$ . Then it holds in  $(\mathbb{R}^m, \|\cdot\|)$  that

$$\rho_K(y^\sigma, y) \leq \min \left\{ 1, \sqrt{2}\sigma \sqrt{m - \ln^- \left( \sigma^2 2\pi m^2 \left( \frac{e}{2} \right)^m \right)} \right\},$$

where  $f^-(h) := \min\{0, f(h)\}$ .

## Ky Fan error estimate

## Theorem (Neubauer, Pikkarainen, 2008)

Let  $y^\sigma$  be a random variable with values in  $\mathbb{R}^m$ . Assume that the distribution of  $y^\sigma$  is  $\mathcal{N}(y, \sigma^2 I)$  with  $\sigma > 0$ . Then it holds in  $(\mathbb{R}^m, \|\cdot\|)$  that

$$\rho_K(y^\sigma, y) \leq \min \left\{ 1, \sqrt{2}\sigma \sqrt{m - \ln^- \left( \sigma^2 2\pi m^2 \left( \frac{e}{2} \right)^m \right)} \right\},$$

where  $f^-(h) := \min\{0, f(h)\}$ .

in practice  $\ln$ -term mostly inactive, then

$$\rho_K(y^\sigma, y) \leq \min \left\{ 1, \sqrt{2}\sigma \sqrt{m} \right\},$$

c.f.  $\mathbb{E}(\|y^\sigma - y\|) \approx \sigma \sqrt{m}$



# Overview

- Introduction
- A Convergence Theorem
- Convergence Rates
- Numerical Examples

Let  $x^\dagger$  be the unique solution of the equation  $Ax = y$  with minimum value of  $\Phi(\cdot)$ .

### Theorem (adapted from Hofinger, '06)

Let  $\alpha, \sigma > 0$ ,  $1 \leq p \leq 2$  and  $N(A) = 0$  for  $p = 1$ . Assume  $w_\lambda \geq c > 0 \forall \lambda \in \Lambda$ . Let  $x_\alpha^{map}$  be the solution of (3). If  $\alpha = \alpha(\sigma)$  is chosen such that  $\hat{\alpha} = \alpha\sigma^2 \rightarrow 0$  and  $\frac{|\ln \sigma|}{\alpha} \rightarrow 0$  as  $\sigma \rightarrow 0$ , then

$$\lim_{\sigma \rightarrow 0} \rho_K(x_\alpha^{map}, x^\dagger) = 0.$$

Let  $x^\dagger$  be the unique solution of the equation  $Ax = y$  with minimum value of  $\Phi(\cdot)$ .

### Theorem (adapted from Hofinger, '06)

Let  $\alpha, \sigma > 0$ ,  $1 \leq p \leq 2$  and  $N(A) = 0$  for  $p = 1$ . Assume  $w_\lambda \geq c > 0 \forall \lambda \in \Lambda$ . Let  $x_\alpha^{map}$  be the solution of (3). If  $\alpha = \alpha(\sigma)$  is chosen such that  $\hat{\alpha} = \alpha\sigma^2 \rightarrow 0$  and  $\frac{|\ln \sigma|}{\alpha} \rightarrow 0$  as  $\sigma \rightarrow 0$ , then

$$\lim_{\sigma \rightarrow 0} \rho_K(x_\alpha^{map}, x^\dagger) = 0.$$

as long as  $\sigma^2 2\pi m^2 \left(\frac{\epsilon}{2}\right)^m > 1$ , then  $\alpha \rightarrow \infty$  is sufficient

Let  $x^\dagger$  be the unique solution of the equation  $Ax = y$  with minimum value of  $\Phi(\cdot)$ .

### Theorem (adapted from Hofinger, '06)

Let  $\alpha, \sigma > 0$ ,  $1 \leq p \leq 2$  and  $N(A) = 0$  for  $p = 1$ . Assume  $w_\lambda \geq c > 0 \forall \lambda \in \Lambda$ . Let  $x_\alpha^{map}$  be the solution of (3). If  $\alpha = \alpha(\sigma)$  is chosen such that  $\hat{\alpha} = \alpha\sigma^2 \rightarrow 0$  and  $\frac{|\ln \sigma|}{\alpha} \rightarrow 0$  as  $\sigma \rightarrow 0$ , then

$$\lim_{\sigma \rightarrow 0} \rho_K(x_\alpha^{map}, x^\dagger) = 0.$$

as long as  $\sigma^2 2\pi m^2 \left(\frac{\epsilon}{2}\right)^m > 1$ , then  $\alpha \rightarrow \infty$  is sufficient  
 main idea for the proof: use Ky Fan metric and split  
 $\Omega = \Omega_{\det}(\sigma) \cup \Omega_{\text{unbound}}(\sigma)$



# Overview

- Introduction
- A Convergence Theorem
- Convergence Rates
- Numerical Examples

# Deterministic Convergence Rate, Daubechies et al, 2004

Assume  $\mathbf{A}$  fulfils, for all  $h \in L^2$

$$A_l^2 \sum_{\lambda} 2^{-2|\lambda|\beta} |\langle h, \psi_{\lambda} \rangle|^2 \leq \|Ah\|^2 \leq A_u^2 \sum_{\lambda} 2^{-2|\lambda|\beta} |\langle h, \psi_{\lambda} \rangle|^2. \quad (4)$$

and  $\|\mathbf{x}^{\dagger}\|_{B_p^s} \leq \varrho$ ,  $\varrho > 0$ . Then

$$\begin{aligned} \sup\{\|\mathbf{x}_{\alpha}^{\text{map}} - \mathbf{x}\| : \mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}, \|\mathbf{A}\mathbf{x} - \mathbf{y}\| \leq \delta, \|\mathbf{x}\|_{B_p^s} \leq \varrho\} \\ < C \left( \frac{\delta + \delta'}{A_l} \right)^{\frac{\varsigma}{\beta + \varsigma}} (\varrho + \varrho')^{\frac{\beta}{\beta + \varsigma}} \end{aligned}$$

with  $\delta' = (\delta^2 + \hat{\alpha}\varrho^p)^{\frac{1}{2}}$  and  $\varrho' = (\varrho^p + \frac{\delta^2}{\hat{\alpha}})^{\frac{1}{p}}$ .

## Theorem

Let all previous assumptions hold. Set  $a_m := \ln\left(\frac{2^m}{2\pi m^2}\right)$ . Then as  $\sigma \rightarrow 0$ ,  $x_\alpha^{map}$  converges with the parameter choice  $\alpha = \alpha(\sigma, \varrho, \beta, \varsigma, p, m, n)$  fulfilling

$$f(\alpha) := \min \left\{ 1, 2 \left( \frac{\sqrt{2}}{A_l} \sigma \sqrt{a_m - 2 \ln \sigma + \frac{\alpha \varrho^p}{2}} \right)^{\frac{\varsigma}{\beta + \varsigma}} \left( \left( \varrho^p + \frac{2}{\alpha} (a_m - 2 \ln \sigma) \right)^{1/p} \right)^{\frac{\beta}{\beta + \varsigma}} \right\} \\ - \frac{\Gamma(\frac{m}{2}, m)}{\Gamma(\frac{m}{2})} - \mathbb{P}(\|x\|_{B_p^s} > \varrho) = 0$$

to the unique solution  $x^\dagger$  and

$$\rho_K(x_\alpha^{map}, x^\dagger) = \mathcal{O} \left( \left( \sigma \sqrt{1 + |\ln \sigma| + \alpha \varrho^p} \right)^{\frac{\varsigma}{\beta + \varsigma}} \left( \left( \varrho^p + \frac{1 + |\ln \sigma|}{\alpha} \right)^{1/p} \right)^{\frac{\beta}{\beta + \varsigma}} \right).$$

where  $\mathbb{P}(\|x_n\|_{B_p^s} > \varrho) = \frac{\Gamma(\frac{n}{p}, \frac{\alpha \varrho^p}{2})}{\Gamma(\frac{n}{p})}$  or  $\mathbb{P}(\|x\|_{B_p^s} > \varrho) = \frac{\mathbb{E}\|x\|_{B_p^s}}{\varrho}$



# Overview

- Introduction
- A Convergence Theorem
- Convergence Rates
- Numerical Examples

- We consider a convolution problem

$$[Ax](s) = [k * x](s) = \int_{\mathbb{R}^d} k(s-t)x(t)dt, \quad s \in \mathbb{R}^d \quad (5)$$

- using a kernel

$$\widehat{k}(\xi) = \frac{c_{\kappa,\beta}}{(1 + \kappa|\xi|^2)^{\beta/2}}, \quad \xi \in \mathbb{R}^d, \quad c_{\kappa,\beta} \text{ s.t. } \|\widehat{k}\|_{L_2(\mathbb{R}^d)} < 1$$

- thus (4) is fulfilled with chosen  $\beta$
- $p = 1, d = 1$



## Iteration [Daubechies, De Mol, Defrise 2004]:

With  $x_0 = 0$ ,

$$x_{k+1} = \mathcal{S}_{\mathbf{w},p}(x_k + A^*(y^\sigma - Ax_k)), \quad k = 1, 2, \dots,$$

where  $\mathcal{S}_{\mathbf{w},p}(h) := \sum_{\lambda \in \Lambda} S_{w_\lambda,p}(\langle h, \psi_\lambda \rangle) \psi_\lambda$  is defined component-wise ( $p = 1$ ) via

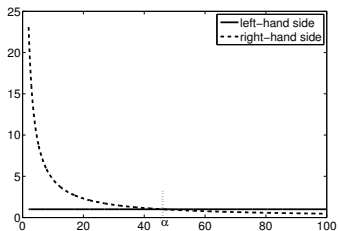
$$S_{w,1}(\xi) := \begin{cases} \xi - \frac{\xi}{2} & \text{if } \xi \geq \frac{\xi}{2} \\ 0 & \text{if } |\xi| < \frac{\xi}{2} \\ \xi + \frac{\xi}{2} & \text{if } \xi \leq -\frac{\xi}{2} \end{cases} .$$

converges since  $\|A\| < 1$

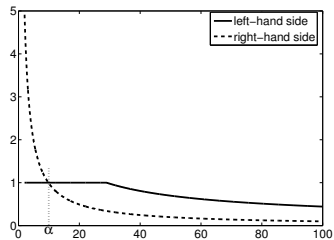
# Parameter choice rule illustrated

$$\sigma = 0.01, m = 2500, \zeta = 0.5, \beta = 1, \varrho = 2.16$$

model (MI),  $s = 1$



model (MII),  $s = 1, r = 2$



## example of a solution

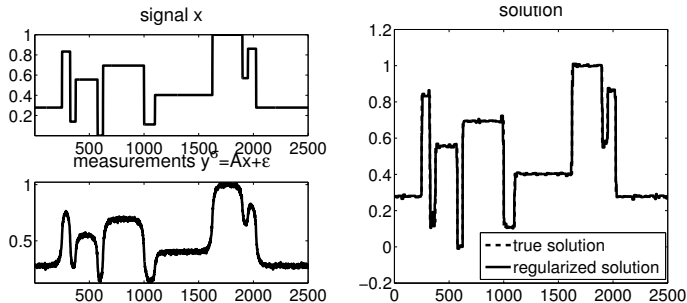


Figure : (MI),  $\sigma = 0.01$ , exact  $\varrho$ ,  $s = 1$ ,  $\beta = 1$ .  $\alpha = 45.85$   
 $\Rightarrow \hat{\alpha} = \alpha\sigma^2 = 0.004585$



comparison of (MI) and (MII),  $m, n$  fixed,  $\sigma \rightarrow 0$

all plots averaged over 20 individual simulations

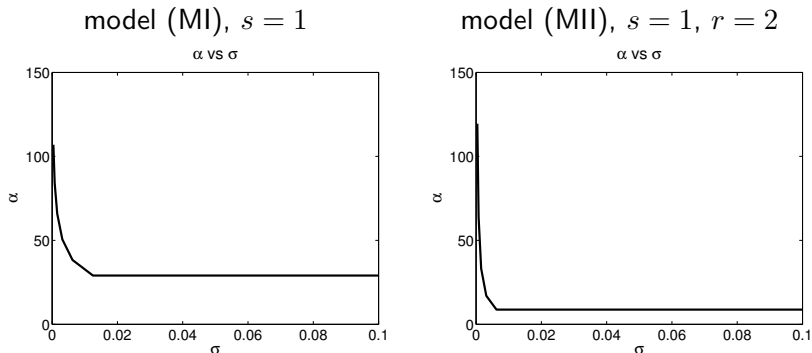


Figure :  $\alpha$  plotted against  $\sigma$ ,  $n = m = 2500$ ,  $\beta = 1$ , exact  $\rho$

# comparison of (MI) and (MII), $m, n$ fixed, $\sigma \rightarrow 0$

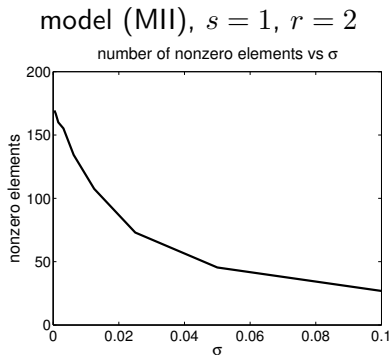
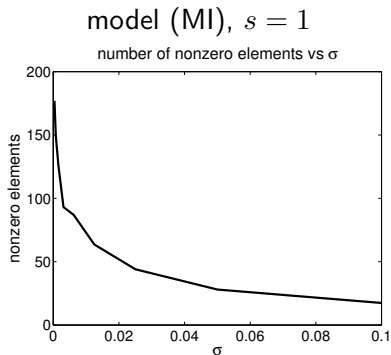


Figure : number of recovered nonzero coefficients plotted against  $\sigma$ ,  
 $n = m = 2500, \beta = 1$ , exact  $\varrho$

# comparison of (MI) and (MII), $m, n$ fixed, $\sigma \rightarrow 0$

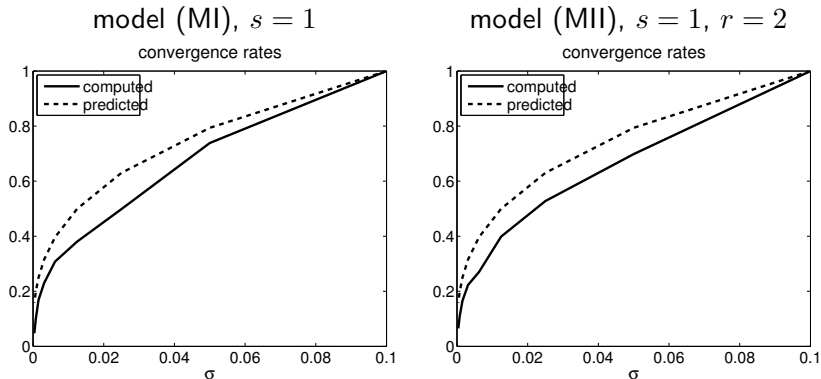
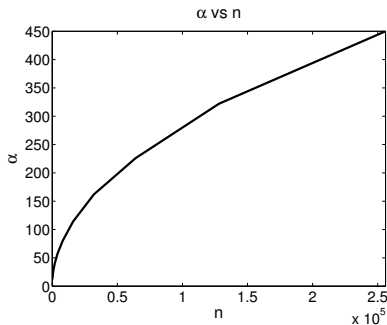


Figure : predicted and observed convergence rates plotted against  $\sigma$ ,  
 $n = m = 2500$ ,  $\beta = 1$ , exact  $\varrho$

# comparison of (MI) and (MII), $\sigma$ fixed, $m, n$ variable

model (MI),  $s = 1$



model (MII),  $s = 1, r = 2$

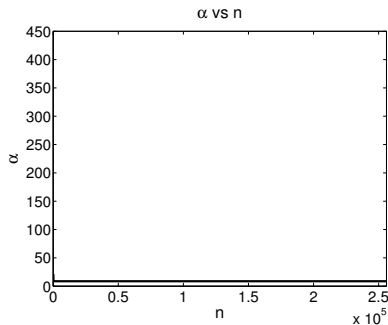


Figure :  $\alpha$  plotted against  $n$ ,  $\sigma = 0.01$ ,  $\beta = 1$ , exact  $\varrho$

# comparison of (MI) and (MII), $\sigma$ fixed, $m, n$ variable

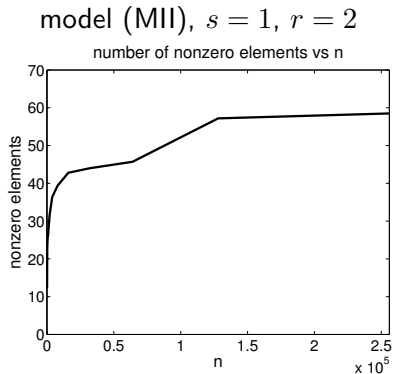
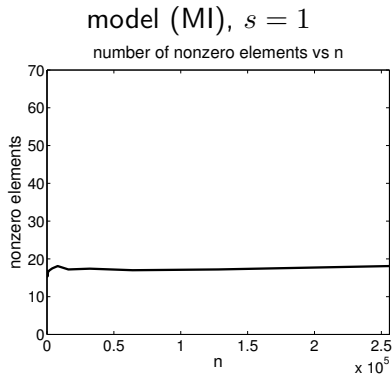


Figure : number of recovered nonzeros plotted against  $n$ ,  $\sigma = 0.01$ ,  $\beta = 1$ , exact  $\rho$

# comparison of (MI) and (MII), $\sigma$ fixed, $m, n$ variable

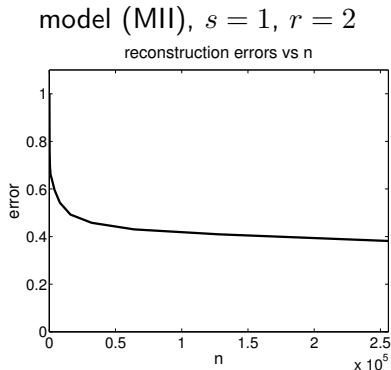
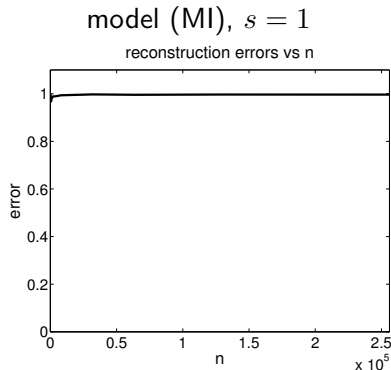


Figure : reconstruction error plotted against  $n$ ,  $\sigma = 0.01$ ,  $\beta = 1$ , exact  $\varrho$

## A 2D convolution example

$$\sigma = 0.1, \beta = 1, \alpha = 130.5, \hat{\alpha} = 1.3$$

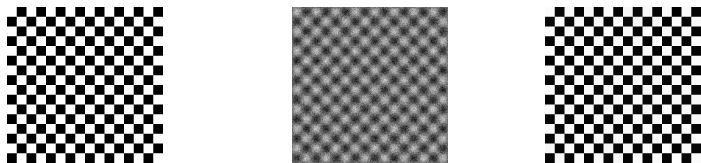







Figure : true solution - measurements - recovered solution

exactly the 68 original coefficients were reconstructed



-  G., R. Ramlau, *A stochastic convergence analysis for Tikhonov-Regularization with sparsity constraints*, submitted
-  M. Lassas, E. Saksman, S. Siltanen, *Discretization-invariant Bayesian inversion and Besov space priors*, Inverse Probl. Imaging, 2009.
-  I. Daubechies, M. Defrise, C. De Mol, *An iterative thresholding algorithm for linear inverse problems with a sparsity constraint*, Comm. Pure Appl. Math. 57, 2004.
-  A. Neubauer, H.K. Pikkarainen, *Convergence results for the Bayesian inversion theory*, J. Inverse Ill-Posed Probl. 16, 2008.
-  J. Kaipio, E. Somersalo, *Statistical and computational inverse problems*, Springer-Verlag, New York, 2005.

Thank you for attention! Are there questions?